



# School of Gauges

## Spy Pro ESP Monitoring Peripheral

AUG 9<sup>th</sup> , 2022

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2. Modbus, Data Pro
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# 1. Scada Sytem

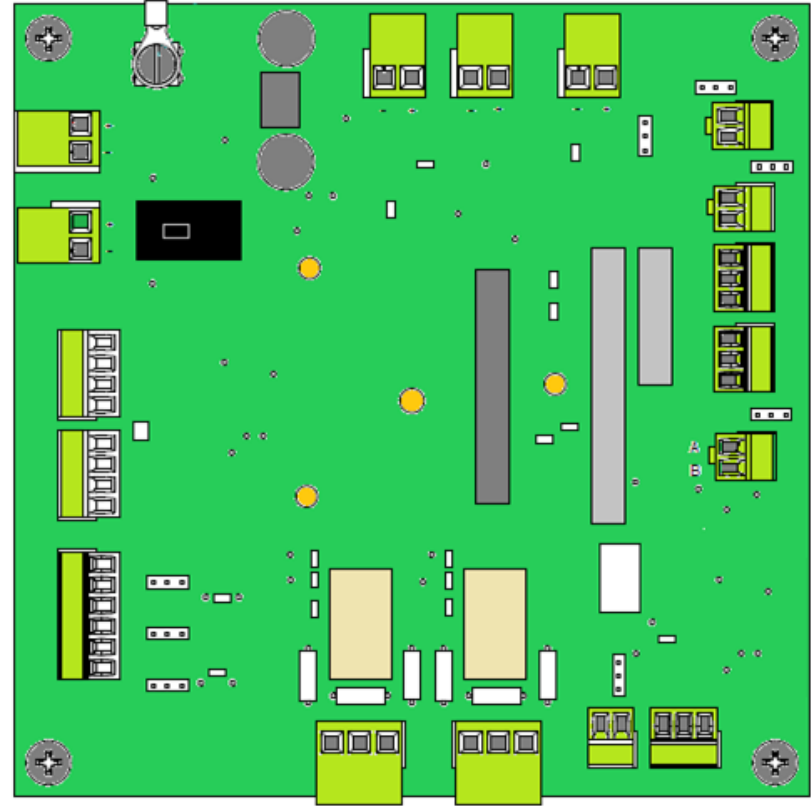
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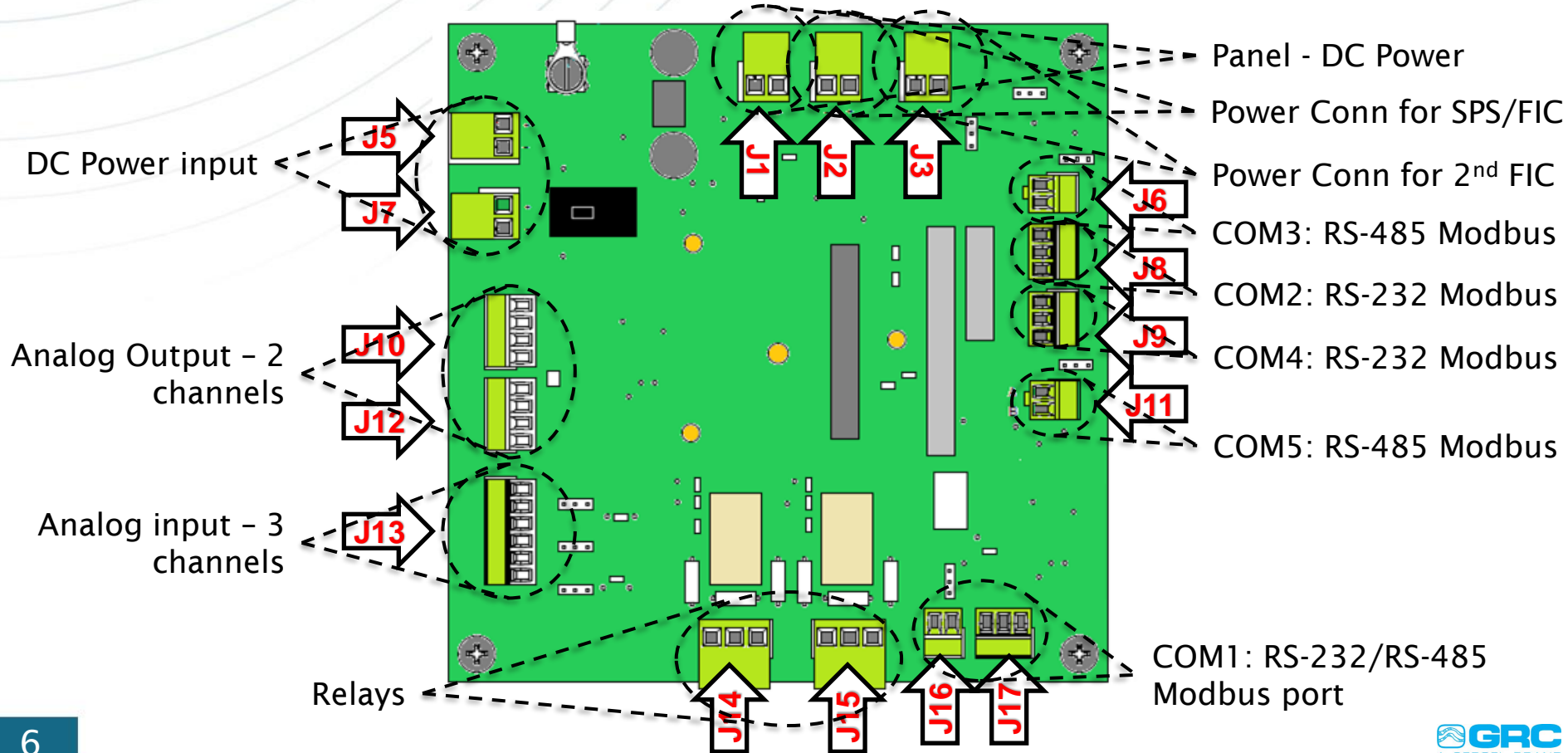
 **GRC**  
A SERCEL BRAND

# Data Pro Peripheral Connections

Connector	Description
J14, J15	Alarm/Relays
JP5, JP6, JP7	Analog input voltage/current selection
J13	Analog input – 3 channels
J12, J10	Analog outputs – 2 channels
J5, J7	DC power input
ST1	Earth ground screw for input power
J2, J3	Power connection for SPS or FIC's
J6	COM3 – RS-485 Modbus slave
J8	COM2 – RS-232 Modbus slave
J11	COM5 – Reserved for SPS/FIC Modbus Connection
J17, J16	COM1 – RS-232/RS-485 Modbus port



# Data Pro Peripheral Connections



# Modbus ports - Data Pro

COM 1 ISO RS485 J16

ISO RS232 J17

COM 2 RS232 J8

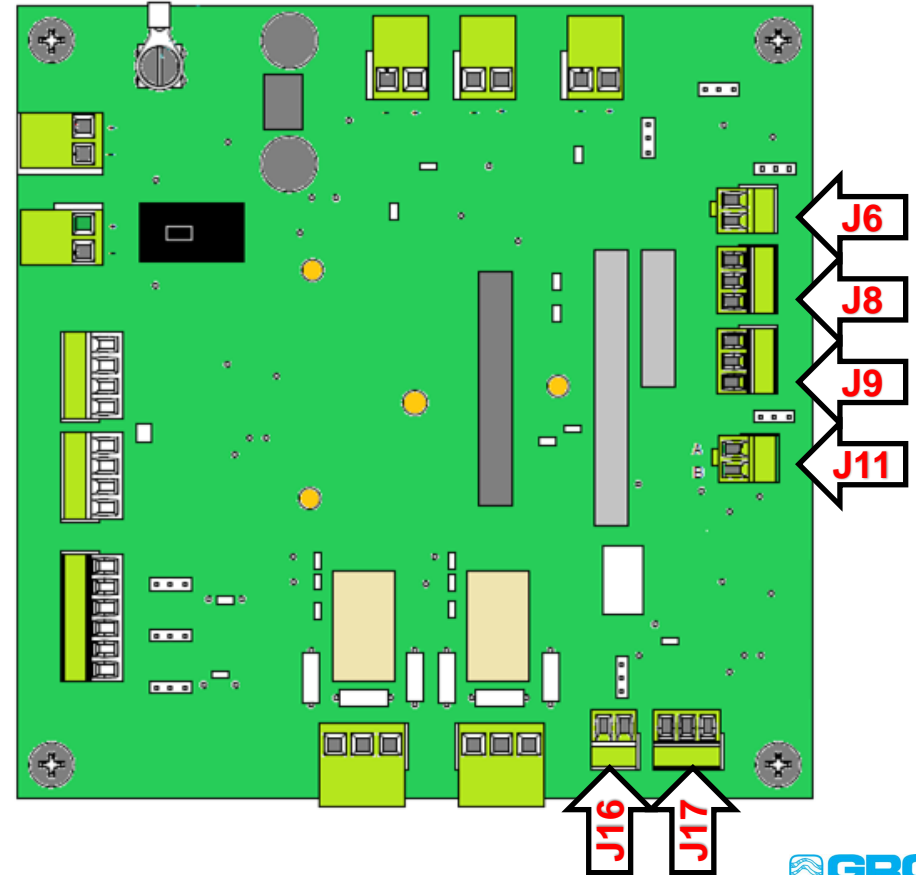
COM 3 RS485 J6

COM 4 RS232 J9

COM 5 RS485 J11

ETH 1 TCP/IP ModBus

ETH 2 TCP/IP ModBus



# Modbus Maps - Data Pro

1. DL4200 - (Default map)  
- (Table 10)
2. SPS-1500 - (Table 11)
3. FIC - (Table 12)
4. SCOUT-3000 - (Table 13)

## 15.0 Appendix 4: Impersonated Scout-3000 Modbus Map

Version = 1.0

WordOrder = High/Low

Register	Register Name	Register Type	Decimal Places	Register Units	Comments
40033	Gauge[1].LastPacketTime	long	1		
40035	Gauge[1].PacketCount	long	0		
40037	Gauge[1].IntakeTemperature	int	1		
40038	Gauge[1].IntakePressure	int	1		
40039	Gauge[1].DischargeTemperature	int	1		
40049	Gauge[1].DischargePressure	int	1		
40041	Gauge[1].MotorTemp	int	1		
40042	Gauge[1].VibrationX	int	2		
40043	Gauge[1].Wye	int	0		
40044	Gauge[1].Conductivity	int	0		
40045	Gauge[1].ToolVoltage	int	1		
40046	Gauge[1].VibrationY	int	2		
40047	Gauge[1].LeakageCurrent	int	2		
40048	Gauge[1].VibrationZ	int	2		

Table 13 - Impersonated Scout-3000 Modbus Map



# How config

## Data Pro (WELL1)

Peripherals 1108052

Time	Pi (Psia)	Ti (F)	Tm (F)	Vx (g)	MOR (Ohm)	Lv (V)	Vy (g)	Lc (mA)
08:08:58	642.10	52.50	60.49	0.42	255	39.9	0.86	2.57
08:08:43	644.20	52.50	60.49	0.42	255	39.9	0.86	2.57
08:08:28	644.20	55.40	60.91	0.42	255	40.0	0.84	2.57
08:08:13	644.20	55.40	60.91	0.42	255	40.0	0.84	2.57
08:07:58	641.90	52.39	61.00	0.42	255	40.0	0.86	2.56

Auto Toggle Tabs

Download

Graph

Menu

Up: 186:42:19/ 75.9% Free 1 Sensor Found



## Enter Password

1234

1	2	3	4	5	6	7	8	9	0
Q	W	E	R	T	Y	U	I	O	P
A	S	D	F	G	H	J	K	L	_
Z	X	C	V	B	N	M	.	-	Del

OK

Cancel

Password: 1234

# How config

## Main Menu

Logging

About

Modbus Setup

Interface Setup

Peripherals

System

Back

## Modbus Setup

Devices	Device	Gauge Port				
Name	COM	Baud/IP	M/S	ADDR	UNIT_ID	Enabled
DATAPRO	TCP	localhost	M	1	1	Y
PROBE1	COM3	9600	S	247	2	N
SPS1	COM1 (4	9600	S	1	3	N

Back

# How config

**Name:** The name of a Modbus device must be unique and cannot contain spaces. The name of the device is used as the file name for the data collected and for reference in other parts of the program.

**COM:** COM will show where the device is connected it will show either the com port number or TCP.

**Baud/IP:** If the device is a serial type device, this field will show the baud rate. If the device is a TCP/IP device, the IP address (or as 'localhost') will be shown.

**M/S:** This field indicates whether the device is a Master or Slave. If the field is set to "S" (slave) then the Data Pro will actively poll that device if a Modbus map is set. If it is set to "M" (master) then the Data Pro will maintain the map and make it available for polling through an unassigned COM or Ethernet port. When "M" is used set the COM to 'TCP' and IP to 'LOCALHOST'.

**ADDR:** This field displays the Modbus slave address that the Data Pro will use to communicate with an attached device.

**Unit\_ID:** This field displays the address, which an external master uses to poll/command the attached device.

**Enabled:** This field indicates whether the device is active or inactive.

Devices	Device	Gauge Port				
Name	COM	Baud/IP	M/S	ADDR	UNIT_ID	Enabled
DATAPRO	TCP	localhost	M	1	1	Y
PROBE1	COM3	9600	S	247	2	N
SPS1	COM1 (4	9600	S	1	3	N

Back

# How config

## Modbus Setup

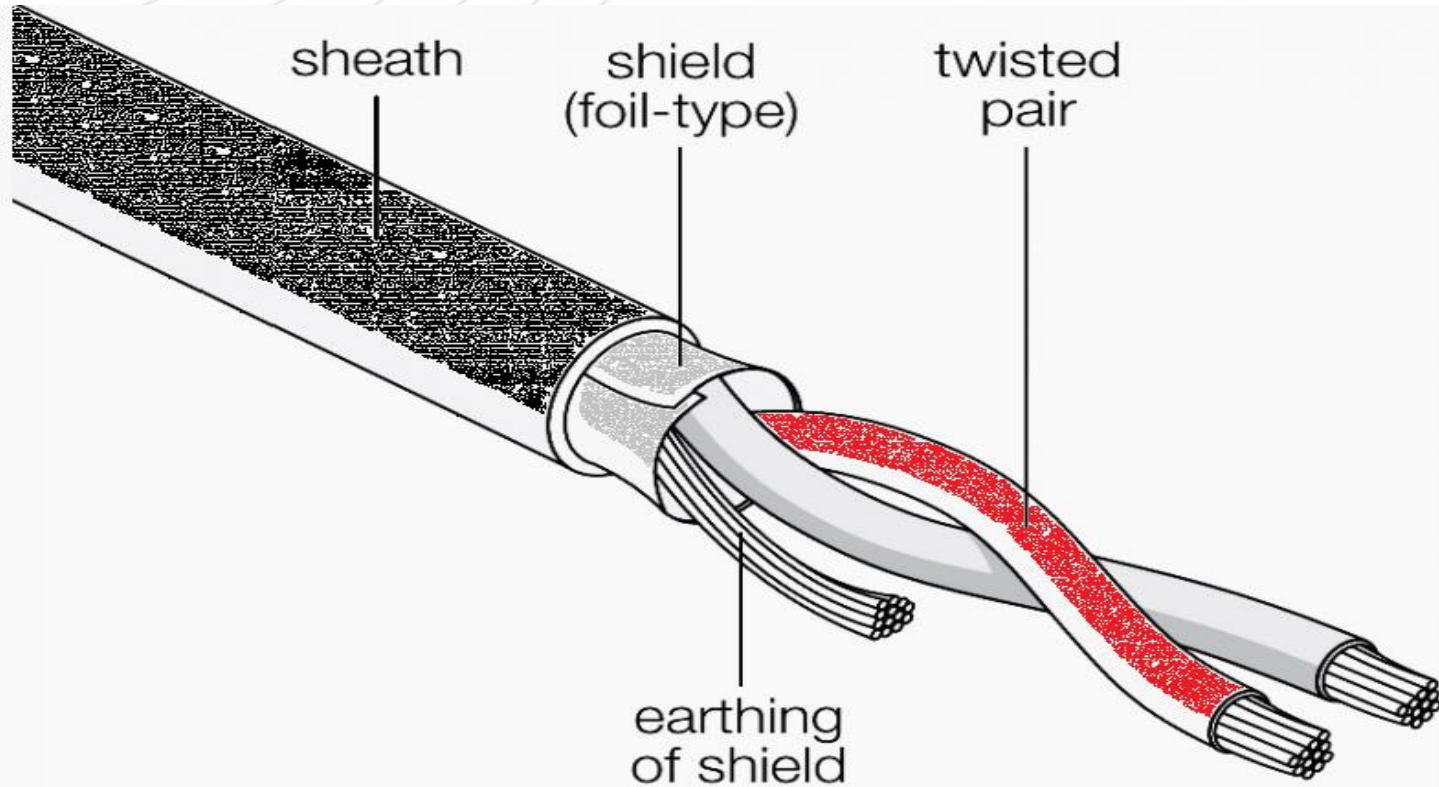
Devices	Device	Gauge Port
Name:	<input type="text" value="SPS1"/>	<input type="button" value="Edit"/>
COM:	<input type="text" value="COM1 (485)"/>	<input type="button" value="Edit"/>
Baud:	<input type="text" value="9600"/>	<input type="button" value="Edit"/>
M/S:	<input type="text" value="S"/>	<input type="button" value="Edit"/>
Addr:	<input type="text" value="1"/>	<input type="button" value="Edit"/>
<input type="checkbox"/> Enabled		
<input type="button" value="Up"/> <input type="button" value="Dn"/> <input type="button" value="Add"/> <input type="button" value="Del"/>		
<input type="button" value="Load"/>		
Map: sps.mbm		
Unit Id:	<input type="text" value="3"/>	<input type="button" value="Edit"/>
<input type="button" value="Back"/>		

# Modbus Wiring

- › Each device has a communication port with these terminals, which are indicated for convenience as A and B. In two terminals, the communication cable is connected so that all the devices participating in the communication are connected in parallel.
- › Reversing the "A" and "B" connections of a device not only prevents it from communicating, but can also stop the entire communication system from functioning due to incorrect forward voltage (bias) found at the device terminals incorrectly connected.
- › To avoid errors when connecting many devices, use wires of the same color for all connections to terminals A and wires of the same color for all connections to terminals B of different devices (eg White for A and blue for B).



# Modbus cable



# Data Pro as Master



# Modbus - Data Pro

Define port to connect

COM 1 ISO RS485 **J16**

ISO RS232 **J17**

COM 2 RS232 **J8**

COM 3 RS485 **J6**

COM 4 RS232 **J9**

COM 5 RS485 **J11** (dedicado a FIC/SPS)

Load \* .mbm file (ModBus map of the slave device)

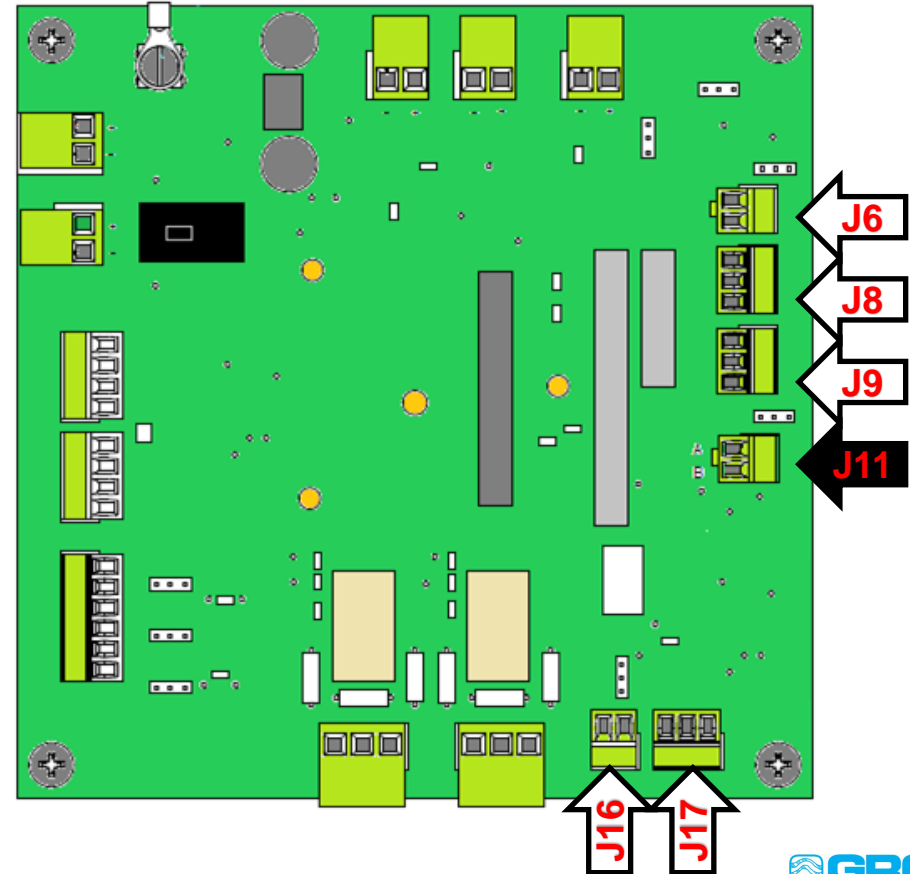
For it:

Set function

typeAddresses / registers

Parameter length

Device ID





# Set as Master

```
TestSpyPro30000 - Notepad
File Edit Format View Help
#Ver 1.11
#Map Header Defines
[Map]
Ver = 1.0
WordOrder= High
Device=Test
Name=TestSpyPro
Model=Test
InputRegStart= 30001
InputRegFrom = 30001
InputRegTo = 33999
RefreshRate=5000
Description=DataPro

[Registers]
#Reg,ParamName, Type (bits_0xMask,byte#,int,long,float), DecPlaces=0, Units='', Description=''
30001,Pres_Int,long, 1, psi
30003,Pres_Dis,long, 1, psi
30005,Temp_Int,long, 1, F
30007,Temp_Mot,long, 1, F
30009,Vib_X,long, 3, G
30011,Vib_Y,long, 3, G
30013,Vib_Z,long, 3, G
30015,Lin_Volt,long, 1, V
30017,Leak_Current,long, 1, mA
30019,Wye_Volt,long, 1, V
```

Address

Length

ModSim32 - [ModSim1]

File Connection Display Window Help

Address: 0001

Length: 22

Device Id: 2

MUDBUS Point Type

04: INPUT REGISTER

Slave Function

Setup Comm Port 5

Protocol:  RTU  ASCII

Baud Rate: 9600

Data Bits: 8

Stop Bits: 1

Parity: NONE

Hardware Flow Control

Wait for DTR from Master  
Delay 100 ms after RTS before transmitting first character

Wait for CTS from Master  
Delay 100 ms after last character before releasing RTS

OK Cancel

# Set as Master

Address

Length

Device Id: 2  
MODBUS Point Type  
Address: 0001  
Length: 22  
MODBUS Point Type: 03: HOLDING REGISTER

\*\*\* NOT CONNECTED! \*\*\*

40001: <00000>  
40002: <01473>  
40003: <00000>  
40004: <01492>  
40005: <00000>  
40006: <01366>  
40007: <00000>  
40008: <00290>  
40009: <00000>  
40010: <08702>  
40011: <00000>  
40012: <08684>  
40013: <00000>  
40014: <01611>  
40015: <00000>  
40016: <00001>  
40017: <00000>  
40018: <00002>  
40019: <00000>  
40020: <00003>  
40021: <00000>  
40022: <00004>

Setup Comm Port 5

Protocol:  RTU  ASCII

Baud Rate: 9600

Data Bits: 8

Stop Bits: 1

Parity: NONE

Hardware Flow Control

Wait for DTR from Master  
Delay: 100 ms after RTS before transmitting first character

Wait for CTS from Master  
Delay: 100 ms after last character before releasing RTS

OK Cancel

Slave Function



```
TestSpyPro40000a - Notepad
File Edit Format View Help
#Ver 1.11
#Map Header Defines
[Map]
Version 1.0
WordOrder= High
Device=Test
Name=TestSpyPro4xa
Model=Test
HoldingRegStart= 40001
HoldingRegFrom = 40001
HoldingRegTo = 41729
RefreshRate=5000
Description=DataPro

[Registers]
#Reg,ParamName, Type (bits_0xMask,byte##,int,long,float), DecPlaces=0, Units='', Description=''
40001,Pres_Int,long, 1, psi
40003,Pres_Dis,long, 1, psi
40005,Temp_Int,long, 1, F
40007,Temp_Mot,long, 1, F
40009,Vib_X,long, 3, G
40011,Vib_Y,long, 3, G
40013,Vib_Z,long, 3, G
40015,Lin_Volt,long, 1, V
40017,Leak_Current,long, 1, mA
40019,Wye_Volt,long, 1, V
```

# Set as Master

**Modbus Setup**

Devices	Device	Gauge Port
Name:	<input type="text" value="SPS1"/>	<input type="button" value="Edit"/>
COM:	<input type="text" value="COM1 (485)"/>	<input type="button" value="Edit"/>
Baud:	<input type="text" value="9600"/>	<input type="button" value="Edit"/>
M/S:	<input type="text" value="S"/>	<input type="button" value="Edit"/>
Addr:	<input type="text" value="1"/>	<input type="button" value="Edit"/>
<input type="checkbox"/> Enabled		
<input type="button" value="Up"/> <input type="button" value="Dn"/> <input type="button" value="Add"/> <input type="button" value="Del"/>		
		<input type="button" value="Load"/>
Map: sps.mbm	Unit Id: <input type="text" value="3"/>	<input type="button" value="Edit"/>
<input type="button" value="Back"/>		



# Mbpoll1 SPS-1500

Modbus Poll - [Mbpoll1 FIC-1500 (1 gauge)]

File Edit Connection Setup Functions Display View Window Help

Tx = 0: Err = 0: ID = 1: F = 03: SR = 1000ms

No connection

	Name	01000
1000		257
1001	Gauge Type	1
1002	Serial Number (int)	-20136
1003		20480
1004	Serial Type	0
1005	Packet Count	4097
1006		0
1007	Error Count	0
1008		2836
1009	Signal Current	0
1010	Last Packet Time	-24332
1011		0
1012	41012- Pressure	605
1013		0
1014	41014- Temperature	6951
1015		0
1016	41018-Vibration X	0
1017		0
1018	41018-Vibration Y	0
1019		0

# Mbpoll1 Data Pro and Simulator

Modbus Poll - [Mbpoll1 Config with Datapro and Simulator]

File Edit Connection Setup Functions Display View Window Help

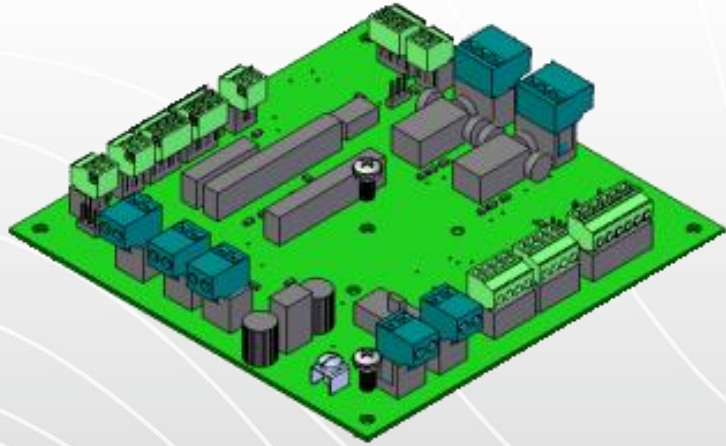
05 06 15 16 17 22 23 TC

Tx = 0: Err = 0: ID = 1: F = 03: SR = 1000ms

No connection

	Name	01000
1000	Serial Number	1403798
1001		--
1002	Last Packet Time	184
1003		--
1004	Packet Count	3
1005		--
1006	Intake Pressure(PSI)	655350
1007		--
1008	Intake Temp(F)	81910
1009		--
1010	Discharge Pressure (PSI)	655350
1011		--
1012	Discharge Temp (F)	0
1013		--
1014	Motor Temp (F)	81910
1015		--
1016	Vx (g)	150
1017		--
1018	Vy (g)	90
1019		--
1020	Vz (g)	0
1021		--
1022	Wye (V)	0
1023		--
1024	MOR(Ohm)	4095
1025		--
1026	LV (Volts)	2940
1027		--
1028	Leakage Current (mA)	0
1029		--





# School of Gauges

## Spy Pro ESP Monitoring Analog IO

AUG 9<sup>th</sup> , 2022

# Input #1, 2, & 3 (Analog Input)

- › The Data Pro has three (3) analog inputs that can be set to voltage or current and have scaling applied

**Alias:** The default name for this parameter is “Analog In”. The alias is an alternate name for the default name referenced in the log files.

**Input Range:** The “Volts/Current” settings must match the jumper settings on the main board for accurate value calculation. Enter a “Min” and “Max” reading for scaling.

**Calculated Values:** These values represent the “Min/Max” values displayed and saved.

**The units:** is a free-hand field without calculation and can be used to identify the reading.

The screenshot shows a web-based configuration interface titled "Peripheral Configuration". At the top, there are tabs for "Input #1", "Input #2", "Input #3", "Output #1", "Output #2", and "Relay #1". The "Input #1" tab is selected. Below the tabs, there is a form for configuring the input. The form includes an "Alias" field with an "Edit" button. The "Input Range" section has radio buttons for "Volts" (selected) and "Current", and input fields for "Min" (0) and "Max" (15), each with an "Edit" button. The "Calculated Values" section has input fields for "Min" (0), "Max" (0), and "Units", each with an "Edit" button. At the bottom of the form, it displays "0v 0ma (Sensor value: 0.000 V (0.000 mA))". A "Back" button is located at the bottom right of the configuration area.



# Output #1 & 2 (Analog Output (4-20mA))

- > The Data Pro has three (2) analog Output (4-20mA)

Enter 4 mA Value for Sensor '20102 (Pi)'

(Last Sensor value: 55.4 Psia)

1	2	3
4	5	6
7	8	9
0	.	Del

Peripheral Configuration

◀ Input #1 Input #2 Input #3 Output #1 Output #2 Relay #1 ▶

Alias

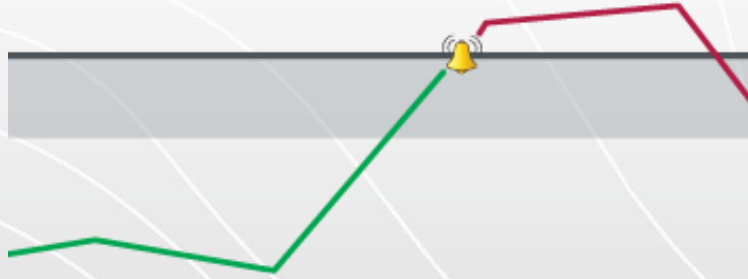
Sensor

4mA value

20mA value

1.06 V (10.602 mA) (Sensor value: 55.4 Psia)





# School of Gauges

## Spy Pro ESP Monitoring Relay

AUG 9<sup>th</sup> , 2022

# Relay Configuration for Alarm/Trip

- › Data Pro configuration example given the following values:
- › To configure Intake Pressure (Pi) and Motor Temperature (Tm) as an alarm parameter.

		Enter Threshold Limite for sensor	Delay value in second (0-10800) seg.
Parameter	Threshold Type	Last sensor value (actual value) Psi/F	0
Pi	<Less Than (manual reset)	200	30
Tm	>Greater Than (manual reset)	392	30

- › To configure Intake Pressure (Pi) and Motor Temperature (Tm) as an trip parameter.

		Enter Threshold Limite for sensor	Delay value in second (0-10800) seg.
Parameter	Threshold Type	Last sensor value (actual value) Psi/F	0
Pi	<Less Than (auto reset)	250	30
Tm	>Greater Than (auto reset)	374	30

# Relay #1 (Relay Configuration)

- › Each relay can have maximum of ten separate threshold conditions and the relay is triggered if anyone out of ten set conditions become true
- › After the relay trips, the main front screen shows the selected channel reading and tripped date and time in red. Follow the menu steps below to configure the Relays (example is for Relay #1 only):

Peripheral Configuration

◀ Input #1 Input #2 Input #3 Output #1 Output #2 Relay #1 ▶

Not Tripped Reset

Threshold	Delay	Reset	Last Reading
1. Off	0	Manual	N/A
2. Off	0	Manual	N/A
3. Off	0	Manual	N/A
4. Off	0	Manual	N/A

Edit Up  
Edit Dn  
Edit  
Edit

Back

Configure Alarm for Relay #1

Threshold Type

- Threshold Disabled/off
- > Greater Than (Manual Reset)
- < Less Than (Manual Reset)
- > Greater Than (Auto Reset)
- < Less Than (Auto Reset)

OK Back

# Relay #1 (Relay Configuration)

- › The latched relays can be set to trigger on any peripheral or gauge parameter
- › The user is encouraged to assign a 'Delay' to each threshold condition to avoid false triggering.

### Configure Alarm for Relay #1

Select sensor to use

<input checked="" type="radio"/> Off	<input type="radio"/> DL Internal Temp
<input type="radio"/> Analog In 1	<input type="radio"/> 20102 (Ti)
<input type="radio"/> Analog In 2	<input type="radio"/> 20102 (Pi)
<input type="radio"/> Analog In 3	<input type="radio"/> 20102 (Vx)
<input type="radio"/> Analog In 4	<input type="radio"/> 20102 (Vy)
<input type="radio"/> DL CPU Temp	<input type="radio"/> DATAPRO (MB)

OK Back

### Enter Threshold limit for Sensor '20102 (Pi)'

(Last Sensor value: 55.4 Psia)

1	2	3
4	5	6
7	8	9
0	.	Del

0

Save Cancel

### Enter Delay value in Seconds for Channel '20102 (Pi)'

(Last Channel value: 55.4 Psia)

1	2	3
4	5	6
7	8	9
0	.	Del

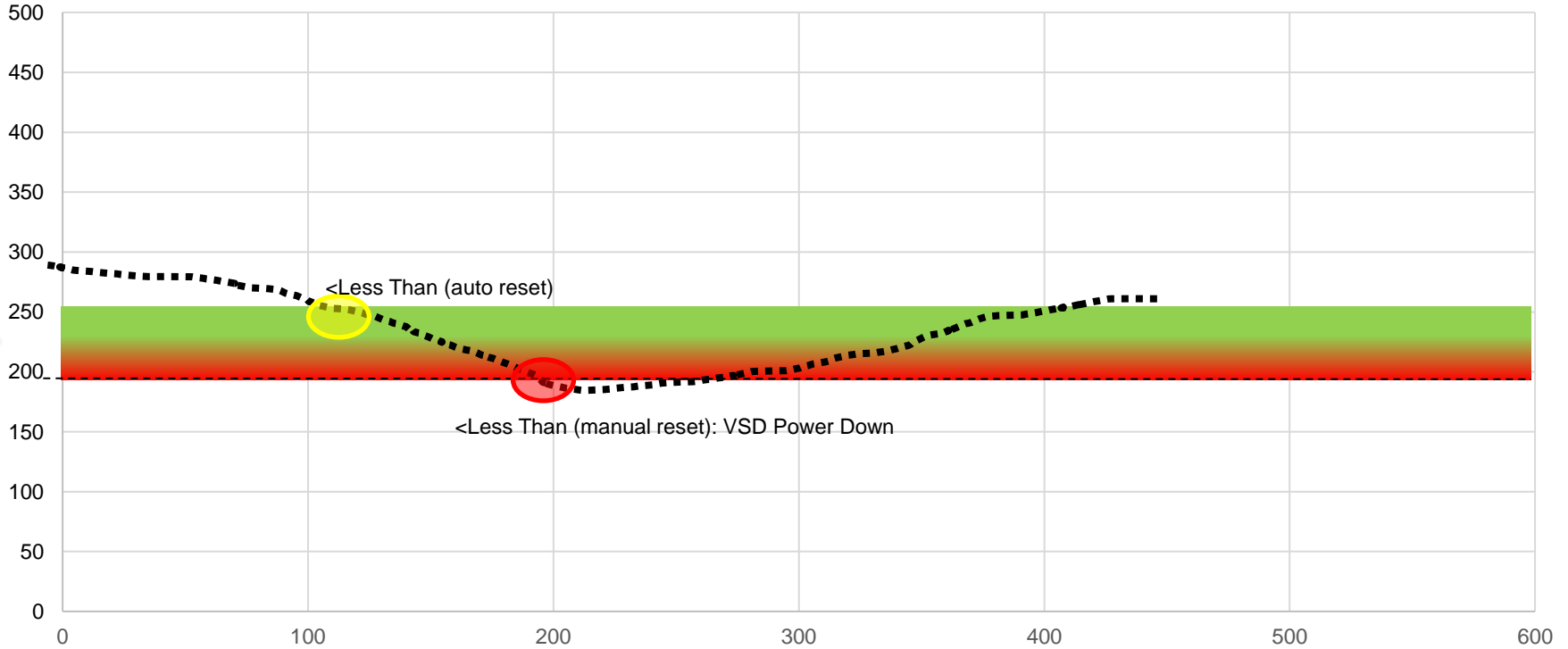
0

Value must be between the min and max.  
Min Value: 0  
Max Value: 10800  
Default Value: 0

Save Cancel

# Data Pro

## Alarm/Trips configuration Pressure Intake (Pi)



# Data Pro

## Alarm/Trips Configuration Motor Temperature (Tm)

